



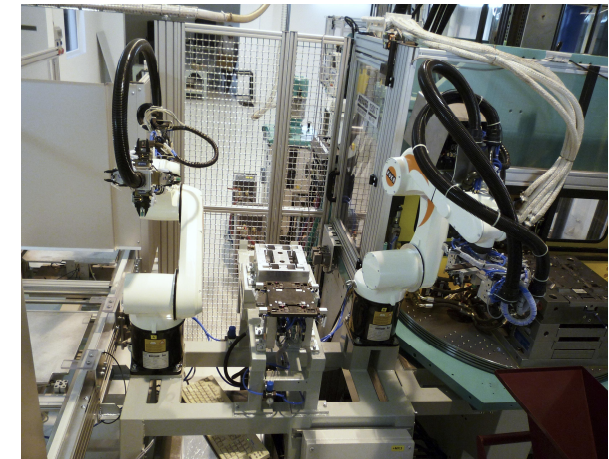
Loading and withdrawing parts from the form of ejection press machine

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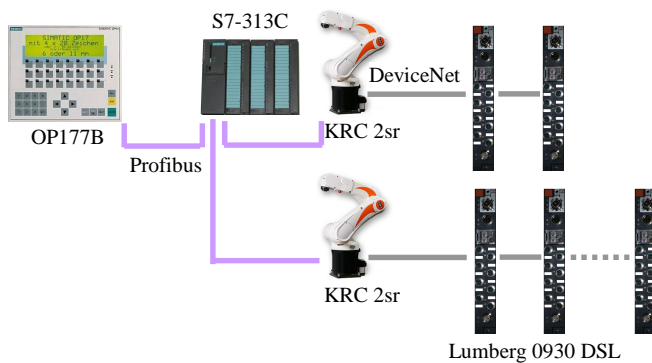
Investor	BRISK Tábor a.s., Tábor, Czech Republic
Realization	2008
Machine delivery	§ Robotic workplace - BLUMENBECKER PRAG s.r.o., Prag Czech Republic § Extruder - ARBURG spol. s r.o., Brno, Czech Republic
Workplace specification	§ 2x robot KUKA KR5 sixx R850 WP
Control system	§ SIMATIC S7-313C-2DP § Robot KUKA KRC2sr § Operating panel OP177B § Remote I/O's Lumberg, type 0930 DSL § Field bus Profibus, DeviceNet, Ethernet § Communication with press via EUROMAP 67.1



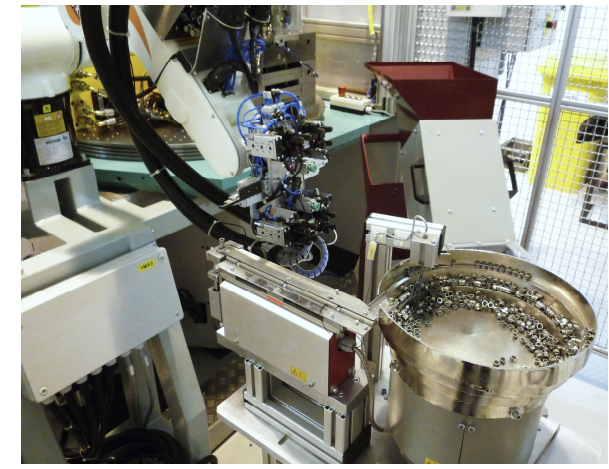
General view on the workplace



Centering and storage unit



Robot A – manipulation with parts in loading palette



Gripper of robot B and vibratory feeder